Sharpening the empirical claims of generative syntax through formalization

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ESSLLI, August 2015

Part 1: Grammars and cognitive hypotheses

What is a grammar? What can grammars do? Concrete illustration of a target: Surprisal

Parts 2-4: Assembling the pieces

Minimalist Grammars (MGs) MGs and MCFGs Probabilities on MGs

Part 5: Learning and wrap-up

Something slightly different: Learning model Recap and open questions

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Part 2

Minimalist Grammars

Outline

5 Notation and Basics

6 Example fragment

Doops and "derivational state"



Outline

5 Notation and Basics

Example fragment

Doops and "derivational state"



Wait a minute!

"I thought the whole point was deciding between candidate sets of primitive derivational operations! Isn't it begging the question to set everything in stone at the beginning like this?"

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"I thought the whole point was deciding between candidate sets of primitive derivational operations! Isn't it begging the question to set everything in stone at the beginning like this?"

- We're not setting this in stone we will look at alternatives.
- But we need a concrete starting point so that we can make the differences concrete.
- What's coming up is meant as a relatively neutral/"mainstream" starting point.

Minimalist Grammars

Defining a grammar in the MG formalism is defining a set Lex of lexical items

- A lexical item is a string with a sequence of features. e.g. *like* :: =d =d v, *mary* :: d, *who* :: d -wh
- Generates the closure of the $Lex \subset Expr$ under two derivational operations:
 - MERGE : $Expr \times Expr \xrightarrow{\text{partial}} Expr$

• MOVE :
$$Expr \xrightarrow{\text{partial}} Expr$$

- Each feature encodes a requirement that must be met by applying a particular derivational operation.
 - MERGE checks =f and f
 - MOVE checks +f and -f
- A derived expression is complete when it has only a single feature remaining unchecked.



Examples



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Notation and Dasies	Example fragment	Loops and derivational state	Derivation tree.
Examples			
MERGE (will :: =v	=d t, eat :: v which :: -wh book :	$= \frac{\text{will ::=dt}}{\text{eat ::}}$	pook ::
MERGE (will :: =d t eat	, John :: which :: -wh book ::	d = John :: < < eat :: which :: - •	th book ::

Notation and R

Examples





Definitions

$$\operatorname{MERGE}\left(e_{1}[=f \alpha], e_{2}[f \beta]\right) = \begin{cases} [\langle e_{1}[\alpha] e_{2}[\beta]] & \text{if } e_{1}[=f \alpha] \in Lex \\ [\rangle e_{2}[\beta] e_{1}[\alpha]] & \text{otherwise} \end{cases}$$

 $MOVE(\mathbf{e}_{1}[+f \alpha]) = [> \mathbf{e}_{2}[\beta] \mathbf{e}_{1}'[\alpha]]$

where $e_2[-f \beta]$ is a unique subtree of $e_1[+f \alpha]$ and e'_1 is like e_1 but with $e_2[-f \beta]$ replaced by an empty leaf node

Shortest Move Constraint

How do we know which subtree should be displaced when we apply ${\ensuremath{\operatorname{MOVE}}\xspace}?$

By stipulation, there can only ever be one candidate. This is the Shortest Move Constraint (SMC).



Shortest Move Constraint

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Q: Multiple wh-movement?

A: Clustering!



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Notation and Basics		
Notation		
=d v or =dp vp?		

Notation and Basics		
Notation		

=d v or =dp vp?

Categorial grammar:

- Primitive symbols for "complete" things, e.g. S, NP
- \bullet Derived symbols for "incomplete" things, e.g. S\NP
- Lexical category can specify "what's missing"

Notation and Basics		
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Traditional X-bar theory:

- Primitive symbols for "incomplete" things, e.g. V, T
- Derived symbols for "complete" things, e.g. VP, TP (= V", T")
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Notation and Basics		
Notation		

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MGs:

- Primitive symbols for "complete" things, like CG
- So t means "a complete projection of T", not "a T head"

Notation and Basics		
Notation comparisor	n	



	Conventional notation
'eat which book' is a VP	VP label on root
'which book' must move	-wh on 'which'
'will' combines with a VP	implicit

Notation comparison



Outline

Notation and Basics

6 Example fragment

7 Loops and "derivational state"



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Notation and Basics	Example hoghene	Loops and "derivational state	
A Minimalist G	rammar		
cake :: d John :: d -k eat :: =d =d v	what :: d -wh who :: d -k -wh e :: =t +wh c		
<i>will</i> :: =v +k t	ϵ :: =t c		

Notation and Basics	Example fragment	Loops and "derivational state"	Derivation trees
A Minimalist G	rammar		
cake :: d John :: d -k eat :: =d =d v will :: =y +k t.	what :: d -wh who :: d -k -wh ϵ :: =t +wh c ϵ :: =t c		



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cake:: d	what:: d - wh
John :: d -k	who :: d -k -wh
eat :: =d =d v	$\epsilon :: =t +wh c$
<i>will</i> :: =v +k t	ϵ :: =t c



cake:: d	what:: d - wh
John :: d -k	who :: d -k -wh
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```
cake :: dwhat :: d -whJohn :: d -kwho :: d -k -wheat :: =d =d v\epsilon :: =t +wh cwill :: =v +k t\epsilon :: =t c
```

John will eat cake	John will cake eat
what John will eat	what John will eat
who will eat cake	who will cake eat

cake :: d John :: d -k eat :: =d =d v will :: =v +k t	what :: d -wh who :: d -k -wh ε :: =t +wh c ε :: =t c	$ \begin{array}{c} S & \to NP \ VP \\ NP & \to \ John \\ NP & \to \ Mary \end{array} $	$\begin{array}{l} VP \ \rightarrow \ V \ NP \\ VP \ \rightarrow \ runs \\ VP \ \rightarrow \ walks \\ V \ \rightarrow \ loves \end{array}$
John will eat ca what John will who will eat ca	ake John will cake eat eat what John will eat ke who will cake eat	John runs John walks John loves John John loves Mary	Mary runs Mary walks Mary loves John Mary loves Mary

First solution: covert movement/agree

cake :: d -k	what :: d -k -wh
John :: d -k	who::d -k -wh
$eat :: =d + \overline{k} = d v$	$\epsilon :: =t +wh c$
will :: =v +k t	ϵ :: =t c

First solution: covert movement/agree

cake :: d -k	what :: d -k -wh
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will :: =v +k t	$\epsilon :: \texttt{=t c}$


First solution: covert movement/agree

cake :: d -k	what :: d -k -wh
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$eat :: =d + \overline{k} = d v$	$\epsilon :: \texttt{=t +wh c}$
will :: =v +k t	ϵ :: =t c



Note order of features on eat!

Second solution

Separate d into subj and obj

cake :: objwhat :: obj -whJohn :: subj -kwho :: subj -k -wheat :: = obj = subj v $\epsilon :: = t +wh c$ will :: = v + k t $\epsilon :: = t c$

Problem "solved":

John will eat cake what John will eat who will eat cake

Outline

Notation and Basics

Example fragment

Doops and "derivational state"



Adding embedded clauses

cake :: obj	what::obj-wh	think :: =c =subj v
John :: subj -k	who :: subj -k -wh	ask ∷ =q =subj v
eat :: =obj =subj v	$\epsilon :: =t +wh q$	Mary :: subj -k
will :: =v +k t	€ :: =t c	

Adding embedded clauses

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John will eat cake	Mary will think John will eat cake	
what John will eat	what Mary will think John will eat	
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cake :: obj	what::obj-wh	think :: =c =subj v
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will :: =v +k t	ε::=t c	

John will eat cake	Mary will think John will eat cake
what John will eat	what Mary will think John will eat
who will eat cake	who Mary will think will eat cake



Notation and Basics	Example fragment	Loops and "derivational state"	
Reminder: "Loop	s" in a CFG		
$\begin{array}{lll} S & \rightarrow & NP \; VP \\ NP & \rightarrow & Det \; N' \\ N' & \rightarrow \; N \\ N' & \rightarrow \; N \; PP \\ PP & \rightarrow \; P \; NP \end{array}$	$\begin{array}{lll} VP & \rightarrow \ runs \\ Det & \rightarrow \ the \\ N & \rightarrow \ dog \\ N & \rightarrow \ cat \\ P & \rightarrow \ near \end{array}$		
S NP VP runs Det N' the N cat	NP Det N' the N F dog P near	S VP runs PP NP Det N' the N cat	

Starting point:



A simple, non-looping completion



A simple, non-looping completion



A simple, non-looping completion



Starting point:



Starting point:















Starting point:

















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Extending with who will ask ...



Which extensions create "loops"?





The SMC ensures that there is a finite number of types (that we care about).



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So any type of the form $\langle \alpha, \ldots, -f\alpha_i, \ldots, -f\alpha_j, \ldots \rangle$ is not useful. Thus there are only a finite number of useful types.

Outline

Notation and Basics

Example fragment

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A possible concern

Question

"But hasn't our eventual derived expression lost the information that 'cake' is a DP?"

Derivations



Derivations







A possible concern

Question

"But hasn't our eventual derived expression lost the information that 'cake' is a DP ?"

Answer

Yes, but only in the same way that John ate cake :: S has also lost this information.

The point is not that we can look at the whole derivation to retrieve that information, the point is that the information has already done its job.



We separate the derivational precedence relation from the part-whole relation

























Context-free structure

$$\begin{array}{rccc} \langle \texttt{=subj v} \rangle & \to & \langle \texttt{=q =subj v} \rangle & \langle q \rangle \\ & \langle q \rangle & \to & \langle \texttt{+wh q}, \texttt{-wh} \rangle \\ \langle \texttt{+wh q}, \texttt{-wh} \rangle & \to & \langle \texttt{=t +wh q} \rangle & \langle \texttt{t}, \texttt{-wh} \rangle \end{array}$$

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General schemas for MERGE steps (approximate):

$$\begin{array}{lll} \langle \gamma, \alpha_1, \dots, \alpha_j, \beta_1, \dots, \beta_k \rangle & \to & \langle \texttt{=} \texttt{f} \gamma, \alpha_1, \dots, \alpha_j \rangle & \langle \texttt{f}, \beta_1, \dots, \beta_k \rangle \\ \langle \gamma, \alpha_1, \dots, \alpha_j, \delta, \beta_1, \dots, \beta_k \rangle & \to & \langle \texttt{=} \texttt{f} \gamma, \alpha_1, \dots, \alpha_j \rangle & \langle \texttt{f} \delta, \beta_1, \dots, \beta_k \rangle \end{array}$$

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- MOVE steps change something without combining it with anything
- Compare with unary CFG rules, or type-raising in CCG, or ...

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